

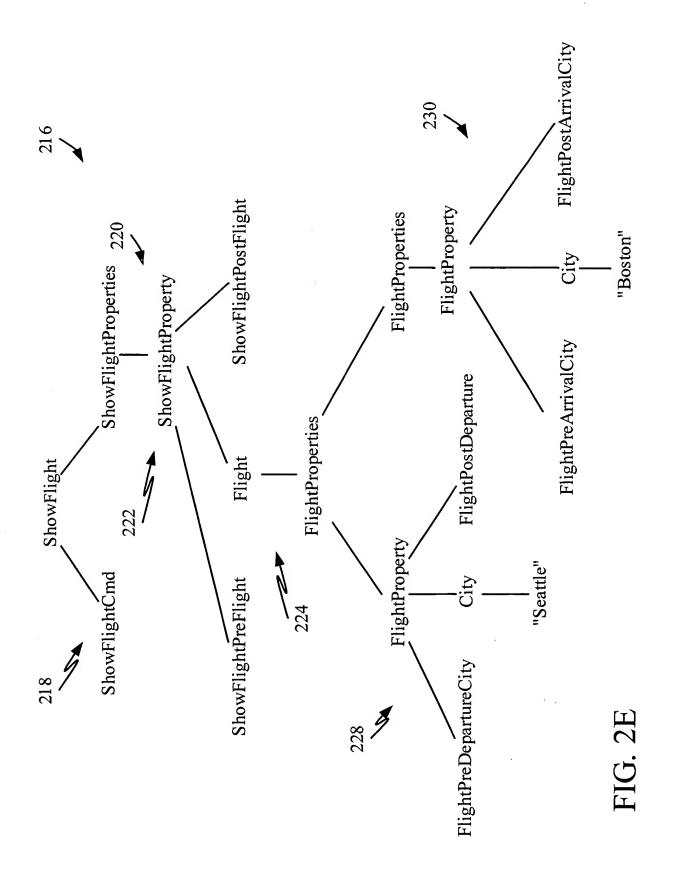
FIG. 2B

```
1. <ShowFlight>→ <ShowFlightCmd><ShowFlightProperties>
```

- 2. <ShowFlightProperties> <ShowFlightProperties>
- 3. <ShowFlightProperty>-> <ShowFlightPreFlight><Flight><ShowFlightPostFlight>
- 4. <Flight> <FlightProperties>
- 5. <FlightProperties <FlightProperties>
- 6. <FlightProperty>--> <FlightPreDepartureCity><City><FlightPostDepartureCity>
- 7. <FlightProperty>→ <FlightPreArrivalCity><City><FlightPostArrivalCity>
- 8. <FlightProperty> --- <FlightPreDepartureTime> <Time> <FlightPostDepartureTime>
- 9. <FlightProperty> --> <FlightPreArrivalTime><Time><FlightPostArrivalTime>

FIG. 2C

FIG. 2D

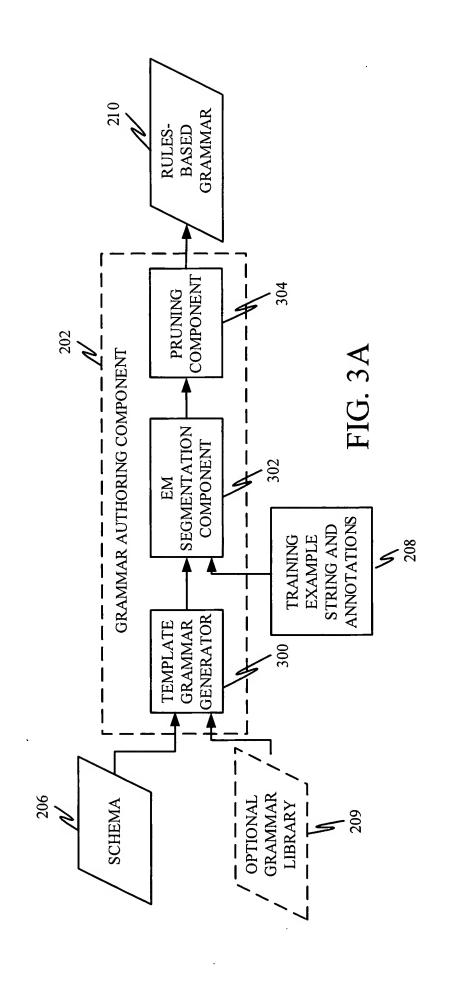


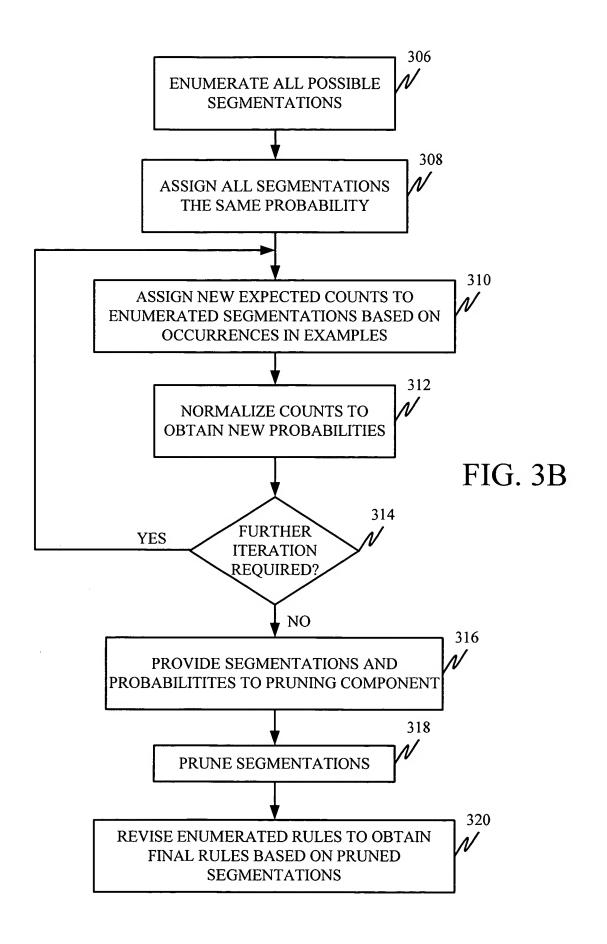
| Example     | Possible Preterminals |                        |
|-------------|-----------------------|------------------------|
| From        | ShowFlightCmd         | FlightPreDepartureCity |
| Flight from | ShowFlightCmd         | FlightPreDepartureCity |
| Flight to   | ShowFlightCmd         | FlightPreArrivalCity   |

## FIG. 2F

| Possible Re-write Rule                      | Count           | Probability | $\bar{C}$ |
|---|-----------------|-------------|-----------|
| SFCmd $\rightarrow \varepsilon$ (empty set) | 1/2+1/3+1/3=7/6 | 7/18        | 7/10      |
| SFCmd→ from                                 | 1/2=3/6         | 3/18        | 3/10      |
| SFCmd→ flight                               | 1/3+1/3=4/6     | 4/18        | :         |
| SFCmd→ flight from                          | 1/3=2/6         | 2/18        | •         |
| SFCmd→ flight to                            | 1/3=2/6         | 2/18        |           |
|   |                 |             |           |
| FPDCity→ ε                                  | 1/2+1/3=5/6     | 5/12        |           |
| FPDCity→ from                               | 1/2+1/3=5/6     | 5/12        |           |
| FPDCity→ flight from                        | 1/3=2/6         | 2/12        |           |
| FPACity→ ε                                  | 1/3=1/3         | 1/3         |           |
| FPACity→ to                                 | 1/3=1/3         | 1/3         |           |
| FPACity→ flight to                          | 1/3=1/3         | 1/3         |           |

FIG. 2G





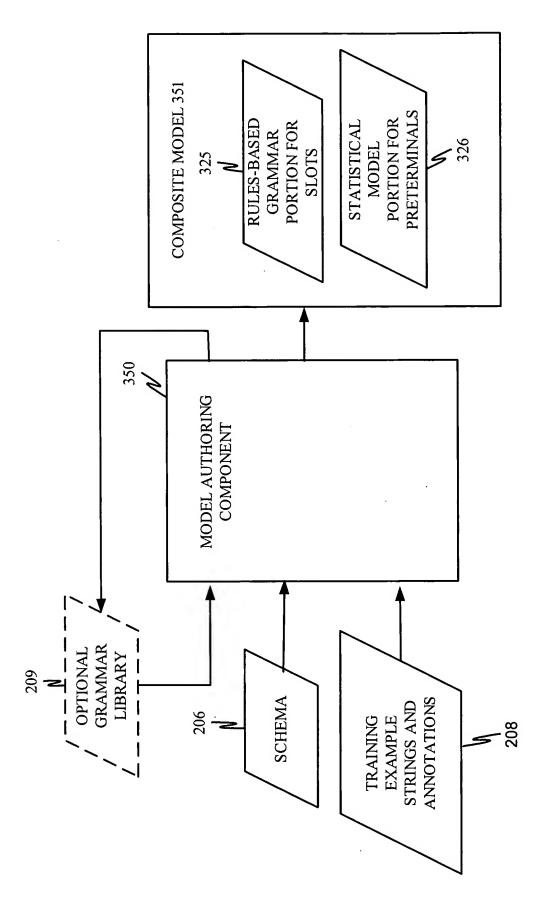


FIG. 4

ShowFlightCmd→ε
ShowFlightCmd→show
ShowFlightCmd→show me
ShowFlightCmd→show me the
ShowFlightCmd→show me the flight

FIG. 5

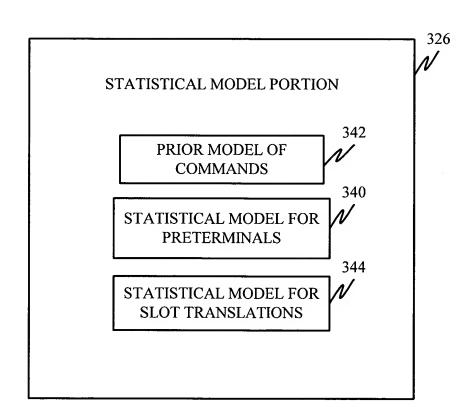


FIG. 6

```
<command name="NewAppt">
     <slot type="Person" name="Attendee"/>
                                                     FIG. 7
     <slot type="Time" name="StartTime"/>
 </command>
<C NewAppt> → <NewApptCmd> {<NewApptProperties>}
<NewApptProperties> > <NewApptProperty>
                      {<NewApptProperties>}
<NewApptProperty> → <NewApptAttendeeProperty> |
                   <NewApptStartTimeProperty>
                                                     FIG. 8
<NewApptAttendeeProperty> →
      {<PreAttendee>} <Person> {<PostAttendee>}
<NewApptStartTimeProperty> →
      {<PreStartTime>} <Time> {<PostStartTime>}
  <NewAppt>
     <a href="">Attendee type="Person">Peter</a>/Attendee>
                                                     FIG. 9
     <StartTime type="Time">five</StartTime>
  </NewAppt>
                                                    FIG. 10
  <NewApptCmd> → new meeting
  <Pre>Attendee> → with
```

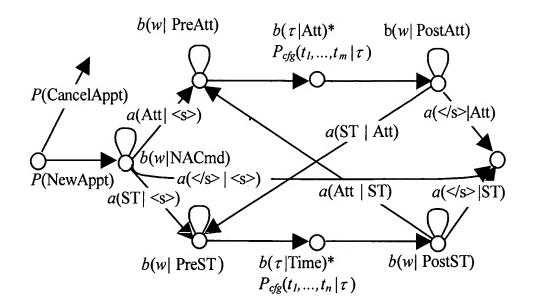


FIG. 11

```
Initialize the model λ with uniform parameterization
do {
foreach NT→a in λ
Compute the expected count C(NT→a) with dynamic programming
foreach NT, set its n-gram parameters in the new model λ':
Partition all the rules for NT into training and held-out sets;
For the rules NT→a in the training set, train the n-gram model for NT using a with the expected count C(NT→a)
Estimate the model smoothing parameters with the held-out counts via
deleted interpolation.
} while (Perplexity(Sample |λ) – Perplexity(Sample | λ') > threshold)
```

FIG. 12

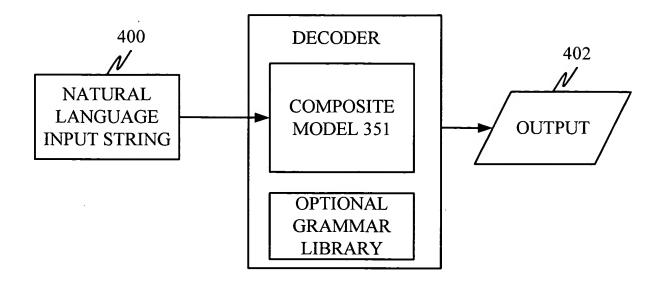


FIG. 13

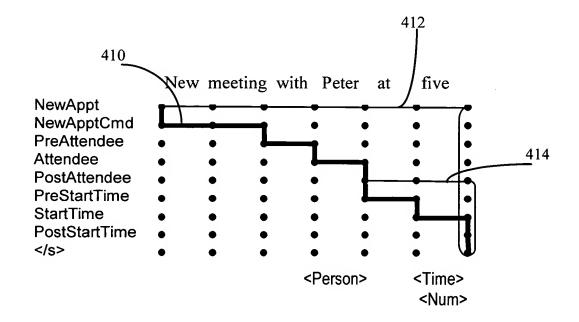
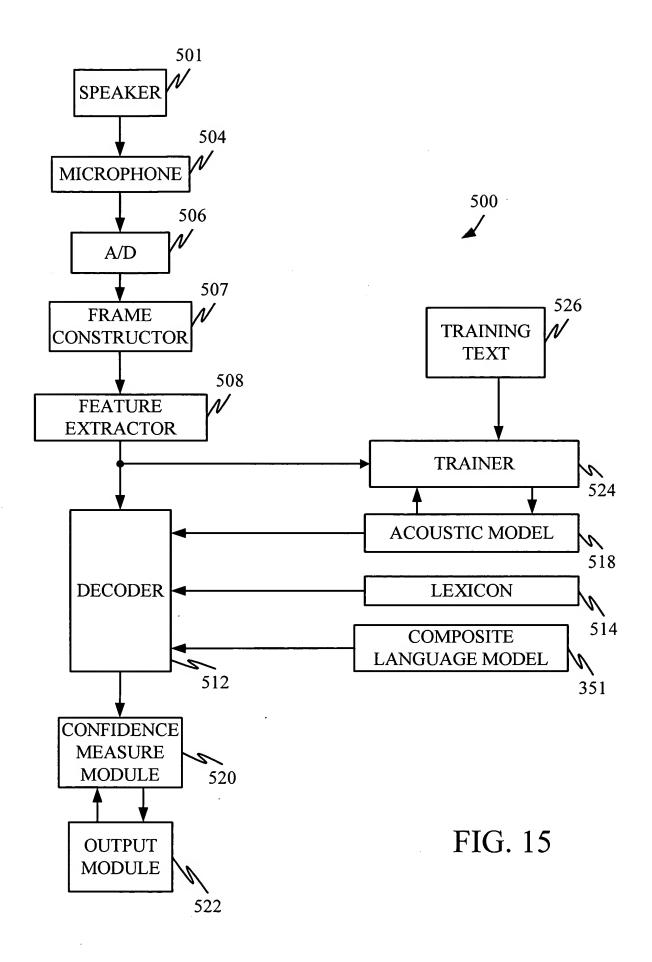


FIG. 14



```
600
```

FIG. 16

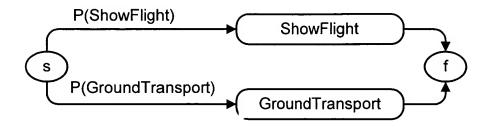
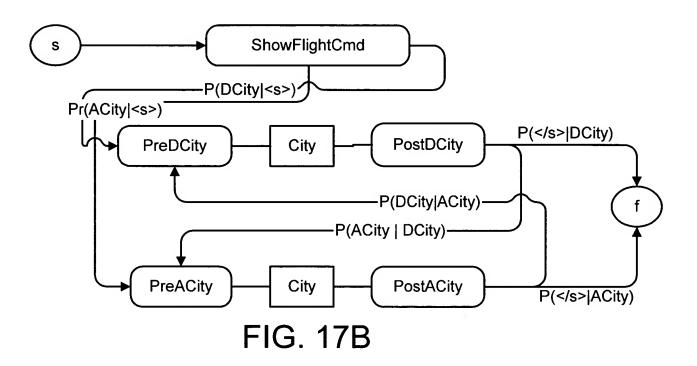


FIG. 17A



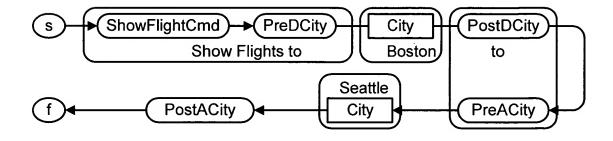


FIG. 17C

